Distributed mobile robot encirclement control of a moving target in a 2D environment

1. Moving target detection using on-board camera
   1. image acquisition and processing
   2. Only one robot acquires image or multirobot can have the images

Reading: vision interception paper

1. Encirclement control
   1. Distributed control
   2. How to use partially available vision information
   3. How to estimate the other robot position?

Reading: encirclement paper; IBVS paper

3. Qbot 2 vision system test and programming